

Final Examination – Solutions

Name: _____

Calculators may be used for simple arithmetic operations only!

1. (15 pts.) \mathbf{A} is a vector field, f is a scalar function. Label each of these identities as either (i) nonsense (gibberish), (ii) meaningful but false, or (iii) correct.

(a) $\nabla \times (f\mathbf{A}) = \nabla f \times \mathbf{A} + f\nabla \times \mathbf{A}$

Correct. To check this it suffices to look at one component:

$$[\nabla \times (f\mathbf{A})]_z = \frac{\partial}{\partial x}(fA_y) - \frac{\partial}{\partial y}(fA_x) = \frac{\partial f}{\partial x}A_y - \frac{\partial f}{\partial y}A_x + f\frac{\partial A_y}{\partial x} - f\frac{\partial A_x}{\partial y} = [\nabla f \times \mathbf{A}]_z + f[\nabla \times \mathbf{A}]_z.$$

(b) $\nabla \times (f\mathbf{A}) = \nabla f \cdot \mathbf{A} + f\nabla \cdot \mathbf{A}$

Nonsense: the left side is a vector but the right side is a scalar.

(c) $\nabla \times (f\mathbf{A}) = \nabla f \times \mathbf{A} - f\nabla \times \mathbf{A}$

Meaningful but false (by comparison with (a)).

2. (Essay – 20 pts.) Prove that for any linear function L , the kernel of L is a subspace of the domain of L . (Along the way it would be a good idea to define “subspace” and “kernel”.)

The kernel is the set of vectors satisfying $L\vec{v} = 0$. We note that $L(\lambda\vec{v} + \vec{u}) = \lambda L\vec{v} + L\vec{u} = 0$ (by definition of linearity), when \vec{v} and \vec{u} are any vectors in the kernel and λ is any scalar. This shows that the kernel is closed under addition and scalar multiplication, so (by definition) it is a subspace.

3. (30 pts.) Find an **ORTHONORMAL** basis of eigenvectors of $A = \begin{pmatrix} 3 & 0 & -1 \\ 0 & 2 & 0 \\ -1 & 0 & 3 \end{pmatrix}$.

The characteristic equation is

$$0 = \det(A - \lambda) = \begin{vmatrix} 3 - \lambda & 0 & -1 \\ 0 & 2 - \lambda & 0 \\ -1 & 0 & 3 - \lambda \end{vmatrix} = (2 - \lambda)[(3 - \lambda)^2 - 1] = (2 - \lambda)[\lambda^2 - 6\lambda + 8] = -(\lambda - 2)^2(\lambda - 4).$$

(Resist the temptation to multiply out the cubic; we want to factor the polynomial, not expand it.)
 $\lambda = 2$ (double root):

$$\begin{pmatrix} 1 & 0 & -1 \\ 0 & 0 & 0 \\ -1 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = 0 \Rightarrow \begin{cases} x = z, \\ y \text{ arbitrary,} \\ z \text{ arbitrary.} \end{cases}$$

Therefore, an ON basis for this subspace is

$$\left\{ \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} \right\}.$$

$\lambda = 4$ (single root):

$$\begin{pmatrix} -1 & 0 & -1 \\ 0 & -2 & 0 \\ -1 & 0 & -1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = 0 \Rightarrow \begin{cases} x = -z, \\ y = 0, \\ z \text{ arbitrary.} \end{cases}$$

Therefore, a normalized eigenvector for this one-dimensional subspace is

$$\frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}.$$

All three vectors go together to form an ON eigenbasis for all of \mathbf{R}^3 .

4. (10 pts.) A function $f(x, y, z)$ satisfies $f(0, 0, 0) = 10$, $\nabla f(0, 0, 0) = 0$, and

$$\left\{ \frac{\partial^2 f}{\partial x_j \partial x_k} \right\} = A \quad (\text{where } A \text{ is the matrix in the previous problem}).$$

(a) Is $(0, 0, 0)$ a maximum, minimum, or saddle point of f ?

A minimum, since all 3 eigenvalues are positive.

(b) What is the best affine approximation to f at $(0, 0, 0)$?

The tangent plane is horizontal, since $\nabla f = 0$. The best approximation is simply the constant function, $f(x) \approx 10$.

5. (30 pts.)

(a) Find a basis of eigenvectors of $M = \begin{pmatrix} 2 & 1 \\ 4 & -1 \end{pmatrix}$.

The characteristic equation is

$$0 = \begin{vmatrix} 2 - \lambda & 1 \\ 4 & -1 - \lambda \end{vmatrix} = (\lambda - 2)(\lambda + 1) - 4 = \lambda^2 - \lambda - 6 = (\lambda - 3)(\lambda + 2).$$

Therefore, the eigenvalues are 3 and -2 .

$$\lambda = 3: \begin{pmatrix} -1 & 1 \\ 4 & -4 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = 0 \Rightarrow x = y. \text{ So an eigenvector is } \vec{v}_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}.$$

$$\lambda = -2: \begin{pmatrix} 4 & 1 \\ 4 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = 0 \Rightarrow y = -4x. \text{ So an eigenvector is } \vec{v}_2 = \begin{pmatrix} 1 \\ -4 \end{pmatrix}.$$

Of course, the vectors should *not* be orthogonal, because the matrix M is not symmetric.

(b) Solve the ODE system
$$\begin{cases} \frac{dx}{dt} = 2x + y, & x(0) = x_0, \\ \frac{dy}{dt} = 4x - y, & y(0) = y_0. \end{cases}$$

Method 1: Let $\vec{r}(t) = \begin{pmatrix} x(t) \\ y(t) \end{pmatrix}$. Then it has the form

$$\vec{r}(t) = c_1 \vec{v}_1 e^{3t} + c_2 \vec{v}_2 e^{-2t}$$

for some constants c_1, c_2 that must be chosen to match the initial conditions:

$$\begin{pmatrix} x_0 \\ y_0 \end{pmatrix} = \begin{pmatrix} c_1 + c_2 \\ c_1 - 4c_2 \end{pmatrix}.$$

Row-reduce:

$$\begin{pmatrix} 1 & 1 & x_0 \\ 1 & -4 & y_0 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & x_0 \\ 0 & -5 & y_0 - x_0 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & \frac{4}{5}x_0 + \frac{1}{5}y_0 \\ 0 & 1 & \frac{1}{5}(x_0 - y_0) \end{pmatrix}.$$

So

$$c_1 = \frac{4}{5}x_0 + \frac{1}{5}y_0, \quad c_2 = \frac{1}{5}(x_0 - y_0).$$

Method 2: Let $D = \begin{pmatrix} 3 & 0 \\ 0 & -2 \end{pmatrix}$, $U = \begin{pmatrix} 1 & 1 \\ 1 & -4 \end{pmatrix}$, $U^{-1} = \frac{1}{5} \begin{pmatrix} 4 & 1 \\ 1 & -1 \end{pmatrix}$. Check that $M = UDU^{-1}$. Now the solution matrix is

$$Ue^{tD}U^{-1} = \frac{1}{5} \begin{pmatrix} 4e^{3t} + e^{-2t} & e^{3t} - e^{-2t} \\ 4e^{3t} - 4e^{-2t} & e^{3t} + 4e^{-2t} \end{pmatrix}.$$

Apply it to the initial data vector:

$$\begin{aligned} \begin{pmatrix} x(t) \\ y(t) \end{pmatrix} &= U \begin{pmatrix} x_0 \\ y_0 \end{pmatrix} \\ &= \frac{x_0}{5} \begin{pmatrix} 4e^{3t} + e^{-2t} \\ 4e^{3t} - 4e^{-2t} \end{pmatrix} + \frac{y_0}{5} \begin{pmatrix} e^{3t} - e^{-2t} \\ e^{3t} + 4e^{-2t} \end{pmatrix} = \frac{4x_0 + y_0}{5} \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{3t} + \frac{x_0 - y_0}{5} \begin{pmatrix} 1 \\ -4 \end{pmatrix} e^{-2t} \end{aligned}$$

in agreement with the other method.

6. (30 pts.) Let $\mathbf{F} = 3x \hat{i} + 2y \hat{j} + z^2 \hat{k}$.

(a) Calculate $\nabla \cdot \mathbf{F}$.

$$3 + 2 + 2z = 2z + 5$$

(b) Calculate $\nabla \times \mathbf{F}$.

$$(0 - 0)\vec{i} + \dots = 0 \quad (\text{since each } F_j \text{ depends only on } x_j)$$

- (c) Calculate $\iint_P \mathbf{F} \cdot d\mathbf{S}$ when P is the portion of the diagonal plane with equation $x = z$ that lies inside the unit cube ($0 < x, y, z < 1$).

As clarified during the test, the normal vector is the upward one ($n_z > 0$). We take x and y as independent variables with $z = x$.

$$dz = \frac{\partial z}{\partial x} dx + \frac{\partial z}{\partial y} dy = dx.$$

$$\begin{aligned} \iint_P (F_x dy dz + F_y dz dx + F_z dx dy) &= \int_0^1 \int_0^1 3x (-dx dy) + \int_0^1 \int_0^1 2y (dx)^2 + \int_0^1 \int_0^1 x^2 dx dy \\ &= \int_0^1 \int_0^1 (x^2 - 3x) dx dy = \frac{1}{3} - \frac{3}{2} = -\frac{7}{6}. \end{aligned}$$

Remark: The negative sign on the first term makes geometrical sense, because the “upward” side of the surface is leaning to the left ($n_x < 0$).

- (d) Calculate $\int_C \mathbf{F} \cdot d\mathbf{r}$ when C is the curve $x = t$, $y = \cos t$, $z = \sin t$ ($0 < t < \pi$).

Because the curl is 0, we may choose any path between $(0, 1, 0)$ and $(\pi, -1, 0)$. So I take $z = 0$ and let $t = y$ run from 1 to -1 with $x = 0$, then let $t = x$ run from 0 to π with $y = -1$.

$$\int \mathbf{F}(\mathbf{r}) \cdot \mathbf{r}'(t) dt = \int_1^{-1} 2y dy + \int_0^\pi 3x dx = 0 + \frac{3\pi^2}{2}.$$

This problem can also be solved by constructing a potential function. Also, it is not too hard to evaluate the integral directly, along the original path.

7. (10 pts.) For whichever of these sets is not linearly independent, find an independent set with the same span.

(a) $\{e^x, e^{-x}, \sinh x, \cosh x\}$

Any two from the list will do.

(b) $\{e^x, xe^{2x}, x^2e^{3x}\}$

independent

8. (25 pts.)

(a) Find all solutions of
$$\begin{cases} x + 2y - z = 10, \\ x + y + 2z = 20. \end{cases}$$

$$\begin{pmatrix} 1 & 2 & -1 & 10 \\ 1 & 1 & 2 & 20 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & 2 & 20 \\ 1 & 2 & -1 & 10 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 1 & 2 & 20 \\ 0 & 1 & -3 & -10 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 0 & 5 & 30 \\ 0 & 1 & -3 & -10 \end{pmatrix}.$$

Thus z is arbitrary and

$$y = -10 + 3z, \quad x = 30 - 5z.$$

(b) Discuss the rank, kernel, and range of the linear function with matrix $\begin{pmatrix} 1 & 2 & -1 \\ 1 & 1 & 2 \end{pmatrix}$.

The rank is 2, since the rows are independent. Therefore, the range is all of \mathbf{R}^2 . Therefore, the kernel has dimension $3 - 2 = 1$. In fact, the kernel is the z -dependent part of the solution found in (a); a basis vector for the kernel is $(-5, 3, 1)^t$.

9. (30 pts.) An inner product is defined by the formula

$$\langle f, g \rangle = \int_0^1 f(t)g(t) dt.$$

Find its first 3 orthogonal polynomials. (Don't bother to normalize the last one.)

$\langle 1, 1 \rangle = \int_0^1 1 dt = 1$, so $p_0 = 1$ is already normalized.

$\langle 1, t \rangle = \int_0^1 t dt = \frac{1}{2}$. Therefore, $p_{1\perp} \equiv t - \frac{1}{2}$ is orthogonal to p_0 . We need to normalize it:

$$\int_0^1 p_{1\perp}^2 dt = \int_0^1 \left(t^2 - t + \frac{1}{4} \right) dt = \left[\frac{t^3}{3} - \frac{t^2}{2} + \frac{t}{4} \right]_0^1 = \frac{1}{12}.$$

Therefore,

$$p_1 = \sqrt{12} \left(t - \frac{1}{2} \right).$$

$$\langle 1, t^2 \rangle = \int_0^1 t^2 dt = \frac{1}{3}.$$

$$\langle p_1, t^2 \rangle = \sqrt{12} \int_0^1 \left(t^3 - \frac{t^2}{2} \right) dt = \sqrt{12} \left(\frac{1}{4} - \frac{1}{6} \right) = \frac{1}{\sqrt{12}}.$$

So $p_{2\parallel} = \frac{1}{3} + \frac{\sqrt{12}}{\sqrt{12}} \left(t - \frac{1}{2} \right) = t - \frac{1}{6}$, and

$$p_{2\perp} = t^2 - t + \frac{1}{6}.$$