

Lecture for Week 6 (Secs. 3.6–9)

# Derivative Miscellany I

## *Implicit differentiation*

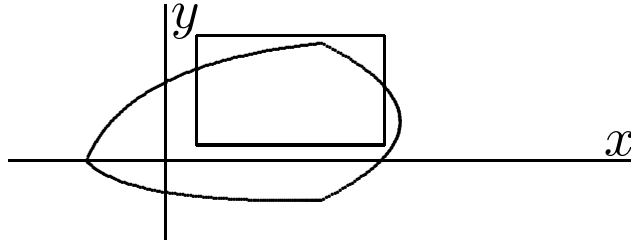
We want to answer questions like this:

1. What is the derivative of  $\tan^{-1} x$ ?
2. What is  $\frac{dy}{dx}$  if

$$x^3 + y^3 + xy^2 + x^2y - 25x - 25y = 0?$$

$$x^3 + y^3 + xy^2 + x^2y - 25x - 25y = 0.$$

Here we don't know how to solve for  $y$  as a function of  $x$ , but we expect that the formula defines a function “implicitly” if we consider a small enough “window” on the graph (to pass the “vertical line test”).



Temporarily assuming this is so, we differentiate the equation with respect to  $x$ , remembering that  $y$  is a function of  $x$ .

$$\begin{aligned}0 &= \frac{d}{dx}(x^3 + y^3 + xy^2 + x^2y - 25x - 25y) \\&= 3x^2 + 3y^2y' + y^2 + 2xyy' + 2xy + x^2y' - 25 - 25y' \\&= (3x^2 + y^2 + 2xy - 25) + y'(3y^2 + 2xy + x^2 - 25).\end{aligned}$$

$$y' = \frac{25 - 3x^2 - y^2 - 2xy}{3y^2 + 2xy + x^2 - 25}.$$

To use this formula, you need to know a point  $(x, y)$  on the curve. You can check that  $(3, 4)$  does satisfy

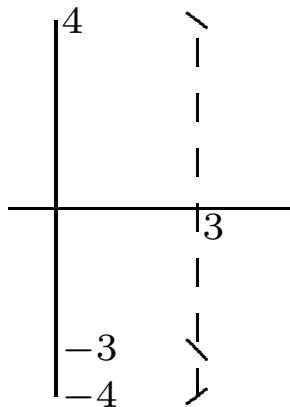
$$x^3 + y^3 + xy^2 + x^2y - 25x - 25y = 0.$$

Plug those numbers into

$$y' = \frac{25 - 3x^2 - y^2 - 2xy}{3y^2 + 2xy + x^2 - 25}$$

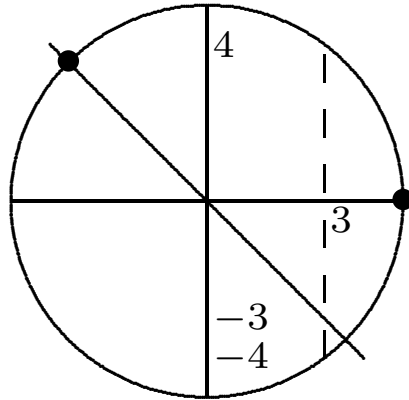
to get  $y' = -\frac{3}{4}$ .

But  $(x, y) = (3, -3)$  also satisfies the equation, and it gives  $y' = -1$ . And  $(3, -4)$  satisfies the equation and gives  $y' = +\frac{3}{4}$ . *Three different* functions are defined near  $x = 3$  by our equation, and each has a different slope.



The curve in this problem is the union of a circle and a line:

$$\begin{aligned} 0 &= x^3 + y^3 + xy^2 + x^2y - 25x - 25y \\ &= (x^2 + y^2 - 25)(x + y). \end{aligned}$$



We can clearly see the three points of intersection with the line  $x = 3$ . Two other interesting points are:

1.  $x = 5, y = 0$  (vertical tangent): The denominator of the formula for  $y$  equals 0, but the numerator does not.
2.  $x = -5/\sqrt{2}, y = 5/\sqrt{2}$  (intersection): Both numerator and denominator vanish, because the slope is finite but not unique.



An important application of implicit differentiation is to find formulas for derivatives of inverse functions, such as  $u = \tan^{-1} v$ . This equation just means  $v = \tan u$ , together with the “branch condition” that  $-\frac{\pi}{2} < u < \frac{\pi}{2}$  (without which  $u$  would not be uniquely defined). So

$$1 = \frac{dv}{dv} = \frac{d}{dv} \tan u = \left( \frac{d}{du} \tan u \right) \frac{du}{dv}.$$

But

$$\frac{d}{du} \tan u = \sec^2 u = 1 + \tan^2 u = 1 + v^2.$$

Putting those two equations together, we get

$$\frac{d}{dv} \tan^{-1} v = \frac{du}{dv} = \left( \frac{d}{du} \tan u \right)^{-1} = \frac{1}{1 + v^2}.$$

Generally speaking, the derivative of an inverse trig function is an algebraic function! We will see more of this in Sec. 4.2.

## Exercise 3.6.39

Show that the curve families

$$y = cx^2, \quad x^2 + 2y^2 = k$$

are orthogonal trajectories of each other.

(That means that every curve in one family (each curve labeled by  $c$ ) is orthogonal to every curve in the other family (labeled by  $k$ ).

For the curves  $y = cx^2$  we have  $\frac{dy}{dx} = 2cx$ .

(No implicit differentiation was needed in this case.) For the curves  $x^2 + 2y^2 = k$  we have

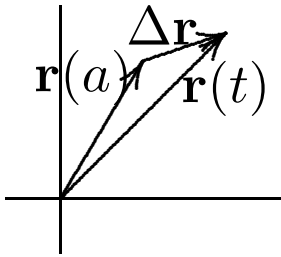
$$2x + 4y \frac{dy}{dx} = 0 \Rightarrow \frac{dy}{dx} = -\frac{x}{2y}.$$

If the curves are orthogonal, the product of the slopes must be  $-1$  (and vice versa). Well, the product is

$$(2cx) \left( -\frac{x}{2y} \right) = -\frac{cx^2}{y} = -1. \quad \blacksquare$$

## *Derivatives of vector functions*

No big surprise here: Conceptually, we are subtracting the “arrows” for two nearby values of the parameter, then dividing by the parameter difference and taking the limit.



$$\mathbf{r}'(a) = \lim_{t \rightarrow a} \frac{\mathbf{r}(t) - \mathbf{r}(a)}{t - a} \equiv \lim_{h \rightarrow 0} \frac{\Delta \mathbf{r}}{h}$$

And calculationally, since our basis vectors do not depend on  $t$ , we just differentiate each component:

$$\frac{d}{dt} \left[ t^2 \hat{\mathbf{i}} + 3t \hat{\mathbf{j}} + 5 \hat{\mathbf{k}} \right] = 2t \hat{\mathbf{i}} + 3 \hat{\mathbf{j}}.$$

## *Second (and higher) derivatives*

This is fairly obvious, too: The second derivative is the derivative of the first derivative.

$$\begin{aligned} s(t) = At^2 + Bt + C &\Rightarrow s'(t) = 2At + B \\ &\Rightarrow s''(t) = 2A. \end{aligned}$$

(This was essentially Exercise 3.8.37.)

The most important application of second derivatives is *acceleration*, the derivative of velocity, which is the derivative of position.

### Exercise 3.8.49

A satellite completes one orbit of Earth at an altitude 1000 km every 1 h 46 min. Find the velocity, speed, and acceleration at each time. (Earth radius = 6600 km.)



The period is  $1\frac{46}{60} = 1.767$  hr. Therefore, the angular speed is  $2\pi/1.767 = 3.557$  radians per hour. The radius of the circle is 7600, so the speed in the orbit is  $7600 \times 3.557 = 27030$  km/h at all times. To represent the velocity we must choose a coordinate system; say that the satellite crosses the  $x$  axis when  $t = 0$  and moves counter-clockwise (so it crosses the  $y$  axis after a quarter period). Then

$$\mathbf{v}(t) = 27030\langle -\sin(3.557t), \cos(3.557t)\rangle.$$

(When  $t = 0$ ,  $\mathbf{v}$  is in the positive  $y$  direction; after a quarter period, it is in the negative  $x$  direction.) The acceleration is the negative of that,

$$\mathbf{a}(t) = 27030 \times 3.557 \langle -\cos(3.557t), -\sin(3.557t) \rangle.$$

Finally, let's find the position function. Its derivative must be  $\mathbf{v}$ , so a good first guess is

$$\mathbf{r}(t) = \frac{27030}{3.557} \langle \cos(3.557t), \sin(3.557t) \rangle.$$

To this we could add any constant vector, but a quick check shows that  $\mathbf{r}(0)$  is in the positive  $x$

direction as we wanted, and this orbit is centered at the origin as it should be. So this is the right answer. Notice that  $\mathbf{a}$  points in the direction opposite to  $\mathbf{r}$  (i.e., toward the center of the orbit), as always for uniform circular motion. ■

## *Slopes and tangents of parametric curves*

What is the slope of a curve defined by parametric equations

$$x = x(t), \quad y = y(t) ?$$

If we had  $y$  as a function of  $x$ , we would just calculate  $\frac{dy}{dx}$ . But we can find the slope without eliminating  $t$  from the equations. It may come as no surprise that the answer is obtained by

“dividing numerator and denominator by  $dt$ ”:

$$\frac{dy}{dx} = \frac{\frac{dy}{dt}}{\frac{dx}{dt}}.$$

The valid proof of this formula is simply an application of the chain rule:

$$\frac{dy}{dt} = \frac{dy}{dx} \frac{dx}{dt}.$$

But, you should be shouting, what if the denominator is 0? If  $\frac{dx}{dt} = 0$  and  $\frac{dy}{dt} \neq 0$ , the curve is vertical at that point, so the slope is properly undefined. If both derivatives are 0, we need to consider another parametrization to get an answer; the moving point has slowed to a standstill at the time of interest, so the parametric derivatives give no information.

To apply the formula, you may need to do some work to determine the correct value of  $t$  to plug in.

### Exercise 3.9.19

At what point does the curve

$$x = t(t^2 - 3), \quad y = 3(t^2 - 3)$$

cross itself? Find equations of both tangents at that point.

If the curve crosses itself, there must be two values of  $t$  that yield the same  $x$  and  $y$ , so

$$t_1(t_1^2 - 3) = t_2(t_2^2 - 3) \quad \text{and} \quad 3(t_1^2 - 3) = 3(t_2^2 - 3).$$

From the second equation,  $t_1 = \pm t_2$ , and so from the first one, either  $t_1 = +t_2$  or  $t_1 = \pm\sqrt{3} = -t_2$ . Only the second possibility is of interest to us. Let's define  $t_1$  to be the positive root.

Now calculate the derivatives:

$$x'(t) = (t^2 - 3) + t(2t) = 3t^2 - 3, \quad y'(t) = 6t.$$



So the slope is

$$\frac{dy}{dx} = \frac{6t}{3t^2 - 3}.$$

Substituting  $t = \pm\sqrt{3}$ , we get

$$\frac{dy}{dx} = \frac{\pm 6\sqrt{3}}{6} = \pm\sqrt{3}.$$

(Unlike the implicit differentiation example earlier, there is no  $\frac{0}{0}$  ambiguity, because the two local curve segments correspond to different values of  $t$ , each with a uniquely defined slope.)

To find the tangent lines we need to know the point, which is easily found from the original formulas:

$$(x, y) = (0, 0).$$

Then in Cartesian terms, the tangent lines are

$$y = \pm\sqrt{3}x.$$

In parametric terms, they are

$$x = (t - \sqrt{3}), \quad y = \sqrt{3}(t - \sqrt{3});$$

$$x = (t + \sqrt{3}), \quad y = -\sqrt{3}(t + \sqrt{3}). \quad \blacksquare$$