

# MATH 308. Differential Equations

## Lecture 7: Higher-order equations

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Item 0: discussing task 2(b) of HW2 (the bifurcation in the family  $y' = y^2 - 4y - c$ , where equilibriums collide and disappear) and the bifurcation in the family  $y' = ay - y^3$  where an equilibrium splits into three.

1.

$$y^{(n)} = f(x, y, y', \dots, y^{(n-1)})$$

is called the  $n$ th order differential equation. Second Newton's law is a second-order ODE (examples: ball attached to a spring:  $mx'' = -kx$ , adding liquid friction:  $mx'' = -kx - cx'$ , swings:  $x'' = -\frac{g}{l} \sin x$  where  $x$  is the angle with the vertical line).

**Initial conditions** for  $n$ th order differential equations have the form  $y(x_0) = y_0, y'(x_0) = y_1, \dots, y^{(n-1)}(x_0) = y_{n-1}$ . For mechanical problems, we get  $x(t_0) = x_0, x'(t_0) = v_0$  — initial position and velocity.

2. **Existence and Uniqueness Theorem** for  $n$ th order equations.

If the function  $f(z_1, \dots, z_n)$  is continuous and its derivatives  $\frac{\partial f}{\partial z_2}, \frac{\partial f}{\partial z_3} \dots$  are continuous around the initial point  $(x_0, y_0, y_1, \dots, y_{n-1})$ , then the solution of the equation  $y^{(n)} = f(x, y, \dots)$  with initial conditions  $y(x_0) = y_0, y'(x_0) = y_1, \dots, y^{(n-1)}(x_0) = y_{n-1}$  exists, is defined on some interval  $(x_0 - \delta, x_0 + \delta)$ , and is unique.

Example:  $f(z_1, z_2, z_3) = z_2 + z_1 z_3$  is continuously differentiable everywhere, thus the theorem applies to  $y'' = f(x, y, y') = y + xy'$ .

3. Linear homogeneous  $n$ -th order equation:

$$y^{(n)} + a_{n-1}(x)y^{(n-1)} + \dots + a_0(x)y = 0$$

(linear with respect to  $y$  and its derivatives).

**Superposition principle:** if two functions  $y_1, y_2$  are solutions of the linear homogeneous equation, then  $(c_1y_1 + c_2y_2)$  is also a solution, where  $c_1, c_2$  are constants. Proof: substitute  $y_1, y_2$  into the equation (we get zero since they are solutions), and add these expressions with coefficients  $c_1, c_2$ .

Example:  $y'' = -y$ . Solutions:  $\sin x, \cos x$  (guessing), thus  $y(x) = c_1 \cos x + c_2 \sin x$  is also a solution for any  $c_1, c_2$ ; for any initial conditions  $y(0) = a, y'(0) = b$ , we can find appropriate  $c_1, c_2$ , namely  $c_1 = a, c_2 = b$ ; thus we have found all solutions due to Existence and Uniqueness theorem.

Example:  $y'' = y$ . Solutions:  $e^x, e^{-x}$  (guessing), thus  $y(x) = c_1e^x + c_2e^{-x}$  is also a solution for any  $c_1, c_2$ ; again, we can satisfy any initial conditions (no proof today), thus we have found all solutions.

4. Linear homogeneous equations with constant coefficients:

$$y^{(n)} + a_{n-1}y^{(n-1)} + \dots + a_0y = 0.$$

A function  $y = e^{\lambda x}$  is a solution if and only if  $\lambda$  is a root of the **characteristic equation**  $\lambda^n + a_{n-1}\lambda^{n-1} + \dots + a_0 = 0$ . (Poll: which functions  $y = e^{\lambda x}$  are solutions of the equation  $y'' + 4y' + 3y = 0$ ? Answer: substituting, get  $\lambda^2e^{\lambda x} + 4\lambda e^{\lambda x} + 3e^{\lambda x} = 0$ , thus  $\lambda^2 + 4\lambda + 3 = 0$ , i.e.  $\lambda = -1, -3$ ).

Using Superposition principle to find all solutions: If the characteristic polynomial has  $n$  different roots  $\lambda_1, \dots, \lambda_n$ , then the general solution of the equation is

$$y(x) = c_1e^{\lambda_1 x} + \dots + c_n e^{\lambda_n x}$$

(Example: for  $y'' + 4y' + 3y = 0$ , the general solution is  $y(x) = c_1e^{-x} + c_2e^{-3x}$ ).

Proofs are postponed: we need to prove that any initial condition can be satisfied.

5. **Complex roots of characteristic polynomials.** Define  $e^{ib} = \cos b + i \sin b$  (complex exponential). Complex exponentials are differentiated normally,  $(e^{\lambda x})' = \lambda e^{\lambda x}$ , thus the previous formula works well.

But we will simplify it to get rid of complex terms: if  $\lambda = a \pm ib$  are complex roots of the characteristic polynomial, we have

$$\begin{aligned} y(x) &= c_1 e^{(a+ib)x} + c_2 e^{(a-ib)x} + \dots = c_1 e^{ax} (\cos bx + i \sin bx) + c_2 e^{ax} (\cos bx - i \sin bx) + \dots \\ &= d_1 e^{ax} \cos bx + d_2 e^{ax} \sin bx + \dots \end{aligned}$$

where  $d_1 = c_1 + c_2$ ,  $d_2 = ic_1 - ic_2$ . Since  $d_1, d_2$  are arbitrary constants, we can just write these real terms  $d_1 e^{ax} \cos bx + d_2 e^{ax} \sin bx + \dots$  in the general formula instead of complex exponentials  $c_1 e^{(a+ib)x} + c_2 e^{(a-ib)x}$ .

Example:  $y'' = -y$ , solutions are  $y(x) = c_1 e^{ix} + c_2 e^{-ix} = d_1 \cos x + d_2 \sin x$ .

6. Repeated roots of the characteristic equation also produce a problem; we postpone this to the next time.