

MATH 311

Topics in Applied Mathematics I

**Lecture 32:**

**Gradient, divergence, and curl.  
Review of integral calculus.**

## Gradient, divergence, and curl

**Gradient** of a scalar field  $f = f(x_1, x_2, \dots, x_n)$  is

$$\text{grad } f = \left( \frac{\partial f}{\partial x_1}, \frac{\partial f}{\partial x_2}, \dots, \frac{\partial f}{\partial x_n} \right).$$

**Divergence** of a vector field  $\mathbf{F} = (F_1, F_2, \dots, F_n)$  is

$$\text{div } \mathbf{F} = \frac{\partial F_1}{\partial x_1} + \frac{\partial F_2}{\partial x_2} + \dots + \frac{\partial F_n}{\partial x_n}.$$

**Curl** of a vector field  $\mathbf{F} = (F_1, F_2, F_3)$  is

$$\text{curl } \mathbf{F} = \left( \frac{\partial F_3}{\partial x_2} - \frac{\partial F_2}{\partial x_3}, \frac{\partial F_1}{\partial x_3} - \frac{\partial F_3}{\partial x_1}, \frac{\partial F_2}{\partial x_1} - \frac{\partial F_1}{\partial x_2} \right).$$

Informally,  $\text{curl } \mathbf{F} = \begin{vmatrix} \mathbf{e}_1 & \mathbf{e}_2 & \mathbf{e}_3 \\ \frac{\partial}{\partial x_1} & \frac{\partial}{\partial x_2} & \frac{\partial}{\partial x_3} \\ F_1 & F_2 & F_3 \end{vmatrix}.$

## Del notation

Gradient, divergence, and curl can be denoted in a compact way using the del (a.k.a. nabla a.k.a. atled) “operator”

$$\nabla = \left( \frac{\partial}{\partial x_1}, \frac{\partial}{\partial x_2}, \dots, \frac{\partial}{\partial x_n} \right).$$

Namely,  $\text{grad } f = \nabla f$ ,  $\text{div } \mathbf{F} = \nabla \cdot \mathbf{F}$ ,  $\text{curl } \mathbf{F} = \nabla \times \mathbf{F}$ .

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**Theorem 1**  $\text{div}(\text{curl } \mathbf{F}) = 0$  wherever the vector field  $\mathbf{F}$  is twice continuously differentiable.

**Theorem 2**  $\text{curl}(\text{grad } f) = \mathbf{0}$  wherever the scalar field  $f$  is twice continuously differentiable.

In the del notation,  $\nabla \cdot (\nabla \times \mathbf{F}) = 0$  and  $\nabla \times (\nabla f) = \mathbf{0}$ .  
Note that  $\nabla \cdot \nabla f = \Delta f$  (the Laplacian, also denoted  $\nabla^2 f$ ).

## Riemann sums and Riemann integral

*Definition.* A **Riemann sum** of a function  $f : [a, b] \rightarrow \mathbb{R}$  with respect to a partition  $P = \{x_0, x_1, \dots, x_n\}$  of  $[a, b]$  generated by samples  $t_j \in [x_{j-1}, x_j]$  is a sum

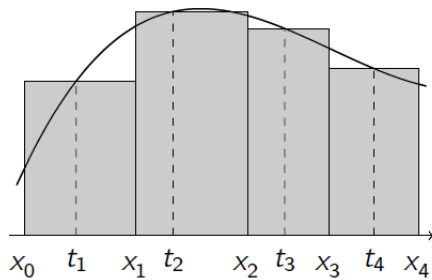
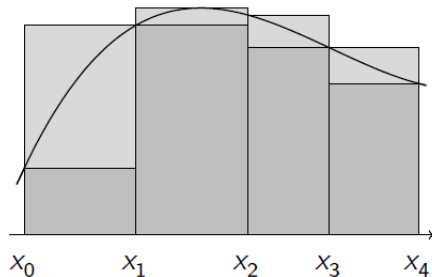
$$\mathcal{S}(f, P, t_j) = \sum_{j=1}^n f(t_j) (x_j - x_{j-1}).$$

*Remark.*  $P = \{x_0, x_1, \dots, x_n\}$  is a partition of  $[a, b]$  if  $a = x_0 < x_1 < \dots < x_{n-1} < x_n = b$ . The norm of the partition  $P$  is  $\|P\| = \max_{1 \leq j \leq n} |x_j - x_{j-1}|$ .

*Definition.* The Riemann sums  $\mathcal{S}(f, P, t_j)$  **converge** to a limit  $I(f)$  as the norm  $\|P\| \rightarrow 0$  if for every  $\varepsilon > 0$  there exists  $\delta > 0$  such that  $\|P\| < \delta$  implies  $|\mathcal{S}(f, P, t_j) - I(f)| < \varepsilon$  for any partition  $P$  and choice of samples  $t_j$ .

If this is the case, then the function  $f$  is called **integrable** on  $[a, b]$  and the limit  $I(f)$  is called the **integral** of  $f$  over  $[a, b]$ , denoted  $\int_a^b f(x) dx$ .

# Riemann sums and Darboux sums



## Integration as a linear operation

**Theorem 1** If functions  $f, g$  are integrable on an interval  $[a, b]$ , then the sum  $f + g$  is also integrable on  $[a, b]$  and

$$\int_a^b (f(x) + g(x)) dx = \int_a^b f(x) dx + \int_a^b g(x) dx.$$

**Theorem 2** If a function  $f$  is integrable on  $[a, b]$ , then for each  $\alpha \in \mathbb{R}$  the scalar multiple  $\alpha f$  is also integrable on  $[a, b]$  and

$$\int_a^b \alpha f(x) dx = \alpha \int_a^b f(x) dx.$$

## More properties of integrals

**Theorem** If a function  $f$  is integrable on  $[a, b]$  and  $f([a, b]) \subset [A, B]$ , then for each continuous function  $g : [A, B] \rightarrow \mathbb{R}$  the composition  $g \circ f$  is also integrable on  $[a, b]$ .

**Theorem** If functions  $f$  and  $g$  are integrable on  $[a, b]$ , then so is  $fg$ .

**Theorem** If a function  $f$  is integrable on  $[a, b]$ , then it is integrable on each subinterval  $[c, d] \subset [a, b]$ . Moreover, for any  $c \in (a, b)$  we have

$$\int_a^b f(x) dx = \int_a^c f(x) dx + \int_c^b f(x) dx.$$

## Comparison theorems for integrals

**Theorem 1** If functions  $f, g$  are integrable on  $[a, b]$  and  $f(x) \leq g(x)$  for all  $x \in [a, b]$ , then

$$\int_a^b f(x) dx \leq \int_a^b g(x) dx.$$

**Theorem 2** If  $f$  is integrable on  $[a, b]$  and  $f(x) \geq 0$  for  $x \in [a, b]$ , then  $\int_a^b f(x) dx \geq 0$ .

**Theorem 3** If  $f$  is integrable on  $[a, b]$ , then the function  $|f|$  is also integrable on  $[a, b]$  and

$$\left| \int_a^b f(x) dx \right| \leq \int_a^b |f(x)| dx.$$



## Fundamental theorem of calculus

**Theorem** If a function  $f$  is continuous on an interval  $[a, b]$ , then the function

$$F(x) = \int_a^x f(t) dt, \quad x \in [a, b],$$

is continuously differentiable on  $[a, b]$ . Moreover,  $F'(x) = f(x)$  for all  $x \in [a, b]$ .

**Theorem** If a function  $F$  is differentiable on  $[a, b]$  and the derivative  $F'$  is integrable on  $[a, b]$ , then

$$\int_a^b F'(x) dx = F(b) - F(a).$$

**Problem.** Evaluate  $\int_0^1 \frac{x(x-3)}{(x-1)^2(x+2)} dx$ .

To evaluate the integral, we need to decompose the rational function  $R(x) = \frac{x(x-3)}{(x-1)^2(x+2)}$  into a sum of partial fractions:

$$\begin{aligned} R(x) &= \frac{a}{x-1} + \frac{b}{(x-1)^2} + \frac{c}{x+2} \\ &= \frac{a(x-1)(x+2) + b(x+2) + c(x-1)^2}{(x-1)^2(x+2)} \\ &= \frac{(a+c)x^2 + (a+b-2c)x + (-2a+2b+c)}{(x-1)^2(x+2)}. \end{aligned}$$

$$\begin{cases} a + c = 1 \\ a + b - 2c = -3 \\ -2a + 2b + c = 0 \end{cases}$$

## Change of the variable in an integral

**Theorem** If  $\phi$  is continuously differentiable on a closed interval  $[a, b]$  and  $f$  is continuous on  $\phi([a, b])$ , then

$$\int_{\phi(a)}^{\phi(b)} f(t) dt = \int_a^b f(\phi(x)) \phi'(x) dx = \int_a^b f(\phi(x)) d\phi(x).$$

*Remarks.* • The **Leibniz differential**  $d\phi$  of the function  $\phi$  is defined by  $d\phi(x) = \phi'(x) dx = \frac{d\phi}{dx} dx$ .

• It is possible that  $\phi(a) \geq \phi(b)$ . Hence we set

$$\int_c^d f(t) dt = - \int_d^c f(t) dt$$

if  $c > d$ . Also, we set the integral to be 0 if  $c = d$ .

•  $t = \phi(x)$  is a proper change of the variable only if the function  $\phi$  is strictly monotone. However the theorem holds even without this assumption.

**Problem.** Evaluate  $\int_0^{1/2} \frac{x}{\sqrt{1-x^2}} dx$ .

To integrate this function, we introduce a new variable  $u = 1 - x^2$ :

$$\begin{aligned} \int_0^{1/2} \frac{x}{\sqrt{1-x^2}} dx &= -\frac{1}{2} \int_0^{1/2} \frac{(1-x^2)'}{\sqrt{1-x^2}} dx \\ &= -\frac{1}{2} \int_0^{1/2} \frac{1}{\sqrt{1-x^2}} d(1-x^2) = -\frac{1}{2} \int_1^{3/4} \frac{1}{\sqrt{u}} du \\ &= \int_{3/4}^1 \frac{1}{2\sqrt{u}} du = \sqrt{u} \Big|_{u=3/4}^1 = 1 - \frac{\sqrt{3}}{2}. \end{aligned}$$