

MATH 614

Dynamical Systems and Chaos

**Lecture 11:**  
**Structural stability (continued).**  
**Sharkovskii's theorem.**

- Structural stability within a parametric family.

Suppose  $f_{\mathbf{p}} : X_{\mathbf{p}} \rightarrow X_{\mathbf{p}}$  is a dynamical system depending on a parameter vector  $\mathbf{p} \in P$ , where  $P \subset \mathbb{R}^k$ . Given  $\mathbf{p}_0 \in P$ , we say that  $f_{\mathbf{p}_0}$  is **structurally stable within the family**  $\{f_{\mathbf{p}}\}$  if there exists  $\varepsilon > 0$  such that for any  $\mathbf{p} \in P$  satisfying  $|\mathbf{p} - \mathbf{p}_0| < \varepsilon$  the system  $f_{\mathbf{p}}$  is topologically conjugate to  $f_{\mathbf{p}_0}$ .

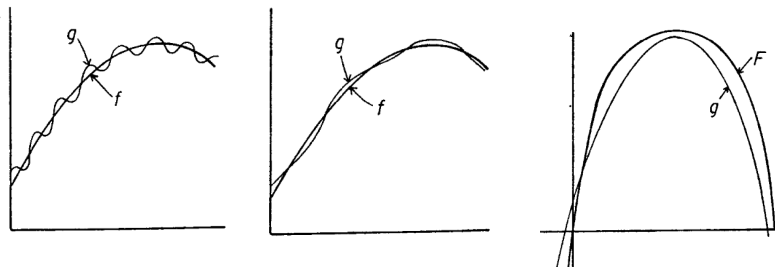
- $C^r$ -structural stability for one-dimensional systems.

Let  $J$  be an interval of the real line. For any integer  $r \geq 0$ , let  $C^r(J)$  denote the set of  $r$  times continuously differentiable functions  $f : J \rightarrow \mathbb{R}$ . The  $C^r$  distance between functions  $f, g \in C^r(J)$  is given by

$$d_r(f, g) = \sup_{x \in J} (|f(x) - g(x)|, |f'(x) - g'(x)|, \dots, |f^{(r)}(x) - g^{(r)}(x)|).$$

We say that a map  $f \in C^r(J)$  is  **$C^r$ -structurally stable** if there exists  $\varepsilon > 0$  such that whenever  $d_r(f, g) < \varepsilon$ , it follows that  $g$  is topologically conjugate to  $f$ .

## Small perturbation

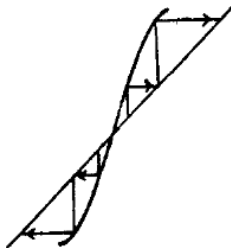


In the first figure, the function  $g$  is a  $C^0$ -small perturbation of  $f$ , but not a  $C^1$ -small one. In the second figure, the functions  $f$  and  $g$  are  $C^1$ -close but not  $C^2$ -close. In the third figure,  $f$  and  $g$  are  $C^2$ -close.

## Examples of structural stability

- Linear map  $f_\lambda : \mathbb{R} \rightarrow \mathbb{R}$ ,  $f_\lambda(x) = \lambda x$ .

The map  $f_\lambda$  is structurally stable within the family  $\{f_\lambda\}$  if and only if  $\lambda \notin \{-1, 0, 1\}$ . Besides, it is  $C^1$ -structurally stable for the same values of  $\lambda$ .



**Proposition** Suppose  $f : [0, \infty) \rightarrow [0, \infty)$  and  $g : [0, \infty) \rightarrow [0, \infty)$  are invertible continuous maps such that  $f(0) = g(0) = 0$ ,  $f(x) > x$  and  $g(x) > x$  for all  $x > 0$ . Then  $f$  and  $g$  are topologically conjugate.

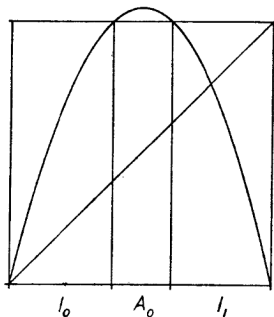
Let  $a, b > 0$ . We can construct a continuous conjugacy  $\phi$  such that  $\phi(f^n(a)) = g^n(b)$  for all  $n$ . Let  $U = (a, f(a))$ . Then  $U$  is a **wandering domain** of the map  $f$ , which means that sets  $\dots, f^{-1}(U), U, f(U), f^2(U), \dots$  are disjoint. Similarly,  $V = (b, g(b))$  is a wandering domain of  $g$ .

$$\begin{array}{ccccccccc}
 \xrightarrow{f} & f^{-1}(U) & \xrightarrow{f} & U & \xrightarrow{f} & f(U) & \xrightarrow{f} & f^2(U) & \xrightarrow{f} \\
 & & & \phi \downarrow & & & & & \\
 \xrightarrow{g} & g^{-1}(V) & \xrightarrow{g} & V & \xrightarrow{g} & g(V) & \xrightarrow{g} & g^2(V) & \xrightarrow{g}
 \end{array}$$

## Examples of structural stability

- Logistic map  $F_\mu : \mathbb{R} \rightarrow \mathbb{R}$ ,  $F_\mu(x) = \mu x(1 - x)$ .

The map  $F_\mu$  is structurally stable within the family  $\{F_\mu\}$  for  $\mu > 4$ . Besides, it is  $C^2$ -structurally stable for  $\mu > 4$  (but not  $C^1$ -structurally stable). It is  $C^1$ -structurally stable for  $\mu > 4$  within the family of unimodal maps.



## Period set

Suppose  $J$  is an interval of the real line and  $f : J \rightarrow J$  is a continuous map. Let  $\mathcal{P}(f)$  be the set of all natural numbers  $n$  for which the map  $f$  admits a periodic point of prime period  $n$  (or, equivalently, a periodic orbit that consists of  $n$  points).

**Question.** Which subsets of  $\mathbb{N}$  can occur as  $\mathcal{P}(f)$ ?

*Examples.* •  $f : \mathbb{R} \rightarrow \mathbb{R}$ ,  $f(x) = x + 1$ .

$\mathcal{P}(f) = \emptyset$ .

•  $f : \mathbb{R} \rightarrow \mathbb{R}$ ,  $f(x) = x$ .

$\mathcal{P}(f) = \{1\}$ .

•  $f : \mathbb{R} \rightarrow \mathbb{R}$ ,  $f(x) = -x$ .

$\mathcal{P}(f) = \{1, 2\}$ .

•  $f : \mathbb{R} \rightarrow \mathbb{R}$ ,  $f(x) = \mu x(1 - x)$ , where  $\mu > 4$ .

The map  $f$  has an invariant set  $\Lambda$  such that the restriction  $f|_{\Lambda}$  is conjugate to the shift on  $\Sigma_{\{0,1\}}$ . Since the shift admits periodic points of all prime periods, so does  $f$ :  $\mathcal{P}(f) = \mathbb{N}$ .

## Sharkovskii's ordering

The **Sharkovskii ordering** is the following strict linear ordering of the natural numbers:

$$\begin{array}{ccccccc} & 3 & \triangleright & 5 & \triangleright & 7 & \triangleright & 9 & \triangleright & \dots \\ \triangleright & 2 \cdot 3 & \triangleright & 2 \cdot 5 & \triangleright & 2 \cdot 7 & \triangleright & 2 \cdot 9 & \triangleright & \dots \\ \triangleright & 2^2 \cdot 3 & \triangleright & 2^2 \cdot 5 & \triangleright & 2^2 \cdot 7 & \triangleright & 2^2 \cdot 9 & \triangleright & \dots \\ & \dots & & \dots & & \dots & & \dots & & \dots \\ \dots & \triangleright & 2^k & \triangleright & \dots & \triangleright & 2^3 & \triangleright & 2^2 & \triangleright & 2 & \triangleright & 1. \end{array}$$

To be precise, for any integers  $k_1, k_2 \geq 0$  and odd natural numbers  $p_1, p_2$  we let  $2^{k_1} p_1 \triangleright 2^{k_2} p_2$  if and only if one of the following conditions holds:

- $k_1 = k_2$  and  $1 < p_1 < p_2$ ;
- $p_1, p_2 > 1$  and  $k_1 < k_2$ ;
- $p_1 > 1$  and  $p_2 = 1$ ;
- $p_1 = p_2 = 1$  and  $k_1 > k_2$ .



## Sharkovskii's Theorem

**Theorem 1 (Sharkovskii)** Suppose  $f : J \rightarrow J$  is a continuous map of an interval  $J \subset \mathbb{R}$ . If  $f$  admits a periodic point of prime period  $n$  and  $n \triangleright m$  for some  $m \in \mathbb{N}$ , then  $f$  admits a periodic point of prime period  $m$  as well.

*Definition.* A subset  $E \subset \mathbb{N}$  is called a **tail** of Sharkovskii's ordering if  $n \in E$  and  $n \triangleright m$  implies  $m \in E$  for all  $m, n \in \mathbb{N}$ .

Sharkovskii's Theorem states that the period set  $\mathcal{P}(f)$  is such a tail. For any  $n \in \mathbb{N}$  the set  $E_n = \{n\} \cup \{m \in \mathbb{N} \mid n \triangleright m\}$  is a tail. The only tails that cannot be represented this way are  $\{2^n \mid n \geq 0\}$  and the empty set.

**Theorem 2** For any tail  $E$  of Sharkovskii's ordering there exists a continuous map  $f : \mathbb{R} \rightarrow \mathbb{R}$  such that  $\mathcal{P}(f) = E$ .

*Remark.* For maps of an interval  $J \subset \mathbb{R}$ , Theorem 2 holds with one exception: if  $J$  is bounded and closed, then  $\mathcal{P}(f) \neq \emptyset$ .

Suppose  $f : J \rightarrow J$  is a continuous map of an interval  $J \subset \mathbb{R}$ . Given two closed bounded intervals  $I_1, I_2 \subset J$ , we write  $\boxed{I_1 \rightarrow I_2}$  if  $f(I_1) \supset I_2$  (i.e., if  $I_1$  covers  $I_2$  under the action of  $f$ ).

**Lemma 1** If  $I \rightarrow I$ , then the interval  $I$  contains a fixed point of the map  $f$ .

*Proof:* Let  $I = [a, b]$ . Since  $f(I) \supset I$ , there exist  $a_0, b_0 \in I$  such that  $f(a_0) = a$ ,  $f(b_0) = b$ . Then a continuous function  $g(x) = f(x) - x$  satisfies  $g(a_0) = a - a_0 \leq 0$  and  $g(b_0) = b - b_0 \geq 0$ . By the Intermediate Value Theorem, we have  $g(c) = 0$  for some  $c$  between  $a_0$  and  $b_0$ . Then  $c \in I$  and  $f(c) = c$ .