

MATH 614

Dynamical Systems and Chaos

Lecture 15:
Maps of the circle.

Circle S^1 .

$$S^1 = \{(x, y) \in \mathbb{R}^2 : |x|^2 + |y|^2 = 1\}$$

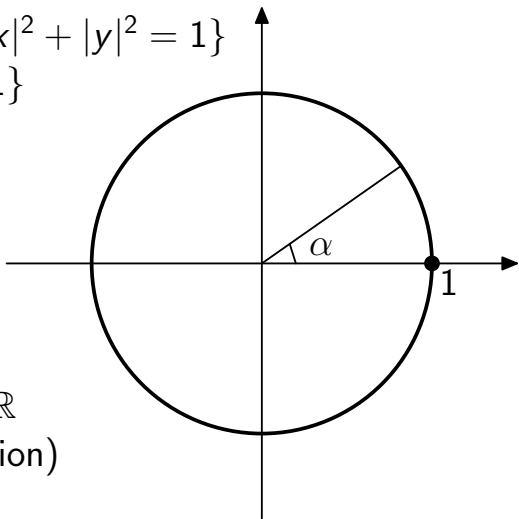
$$S^1 = \{z \in \mathbb{C} : |z| = 1\}$$

$$\mathbb{T}^1 = \mathbb{R}/\mathbb{Z}$$

$$\mathbb{T}^1 = \mathbb{R}/2\pi\mathbb{Z}$$

$\alpha : S^1 \rightarrow [0, 2\pi)$,
angular coordinate

$\alpha : S^1 \rightarrow \mathbb{R}/2\pi\mathbb{Z} \rightarrow \mathbb{R}$
(multi-valued function)



$$\phi : \mathbb{R} \rightarrow S^1,$$

$$\phi(x) = (\cos x, \sin x), \quad S^1 \subset \mathbb{R}^2.$$

$$\phi(x) = e^{ix} = \cos x + i \sin x, \quad S^1 \subset \mathbb{C}.$$

ϕ : wrapping map

$$\phi(x + 2\pi k) = \phi(x), \quad k \in \mathbb{Z}.$$

$\alpha \in \mathbb{R}$ is an angular coordinate of $x \in S^1$ if and only if $\phi(\alpha) = x$.

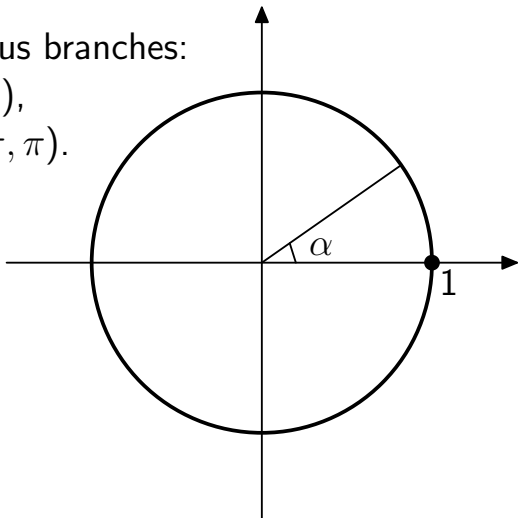
For any arc $\gamma \subset S^1$ there exists a continuous branch $\alpha : \gamma \rightarrow \mathbb{R}$ of the angular coordinate.

If $\alpha_1 : \gamma \rightarrow \mathbb{R}$ and $\alpha_2 : \gamma \rightarrow \mathbb{R}$ are two continuous branches then $\alpha_1 - \alpha_2$ is a constant $2\pi k$, $k \in \mathbb{Z}$.

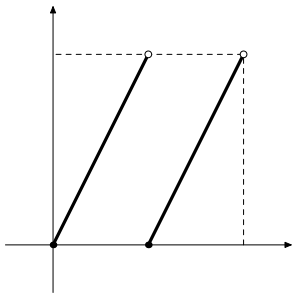
Examples of continuous branches:

$$\alpha : S^1 \setminus \{1\} \rightarrow (0, 2\pi),$$

$$\alpha : S^1 \setminus \{-1\} \rightarrow (-\pi, \pi).$$



Example. $f : S^1 \rightarrow S^1$, $f : z \mapsto z^2$ (**doubling map**),
in angular coordinates: $\alpha \mapsto 2\alpha \pmod{2\pi}$.



The doubling map: smooth, 2-to-1, no critical points.

Theorem The doubling map is chaotic.

Sketch of the proof: If γ is a short arc, then $f(\gamma)$ is an arc twice as long (\implies expansiveness). Moreover, $f^n(\gamma) = S^1$ for n large enough (\implies topological transitivity).

α has finite orbit if $\alpha = 2\pi m/k$, where m and k are coprime integers. α is periodic if k is odd.

Orientation-preserving and orientation-reversing

The real line \mathbb{R} has two orientations.

For maps of an interval:

orientation-preserving = monotone increasing,

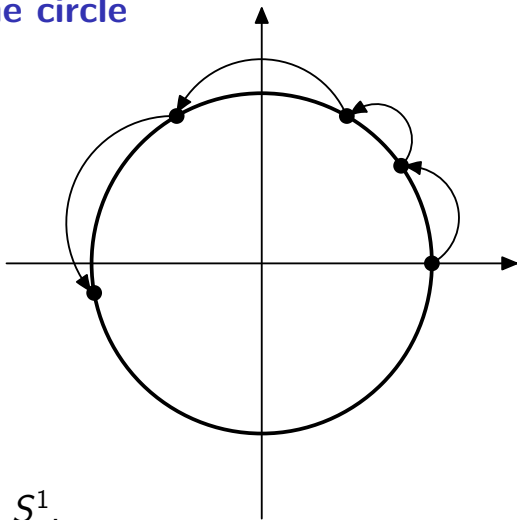
orientation-reversing = monotone decreasing.

The circle S^1 also has two orientations
(clockwise and counterclockwise).

Given a map $f : S^1 \rightarrow S^1$, we say that a map $F : \mathbb{R} \rightarrow \mathbb{R}$ is a **lift** of f if $f \circ \phi = \phi \circ F$, where $\phi : \mathbb{R} \rightarrow S^1$ is the wrapping map. Any continuous map $f : S^1 \rightarrow S^1$ admits a continuous lift F . The lift satisfies $F(x + 2\pi) - F(x) = 2\pi k$ for some $k \in \mathbb{Z}$ and all $x \in \mathbb{R}$. If F_0 is another continuous lift of f , then $F - F_0$ is a constant function.

A continuous map $f : S^1 \rightarrow S^1$ is **orientation-preserving** (resp., **orientation-reversing**) if so is the continuous lift of f .

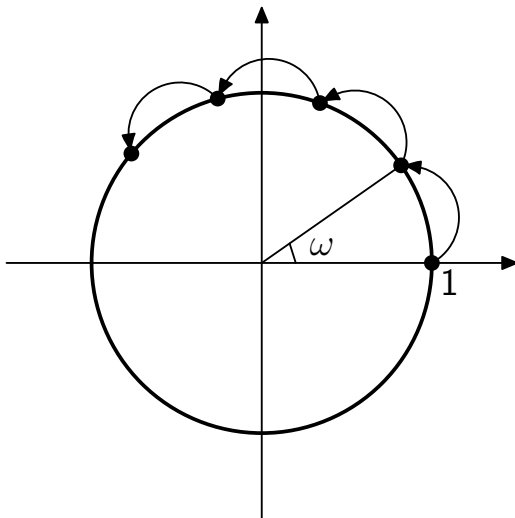
Maps of the circle



$$f : S^1 \rightarrow S^1,$$

f an orientation-preserving homeomorphism.

Rotations of the circle



Rotations of the circle

$R_\omega : S^1 \rightarrow S^1$, rotation by angle $\omega \in \mathbb{R}$.

$R_\omega(z) = e^{i\omega}z$, complex coordinate z ;

$R_\omega(\alpha) = \alpha + \omega \pmod{2\pi}$, angular coordinate α .

Each R_ω is an orientation-preserving diffeomorphism;

each R_ω is an isometry;

each R_ω preserves Lebesgue measure on S^1 .

R_ω is a one-parameter family of maps.

R_ω is a **transformation group**.

Indeed, $R_{\omega_1}R_{\omega_2} = R_{\omega_1+\omega_2}$, $R_\omega^{-1} = R_{-\omega}$.

It follows that $R_\omega^n = R_{n\omega}$, $n = 1, 2, \dots$

Also, $R_0 = \text{id}$ and $R_{\omega+2\pi k} = R_\omega$, $k \in \mathbb{Z}$.

An angle ω is called **rational** if $\omega = r\pi$, $r \in \mathbb{Q}$.
Otherwise ω is an **irrational** angle.

If ω is a rational angle then R_ω is a periodic map.
All points of S^1 are periodic of the same period.

If $\omega = 2\pi m/n$, where m and n are coprime integers, $n > 0$, then the period of R_ω is n .

If ω is irrational then R_ω has no periodic points.

If ω is irrational then R_ω is **minimal**: each orbit is dense in S^1 .

If ω is irrational then each orbit of R_ω is **uniformly distributed** in S^1 .

Minimality

Theorem (Jacobi) Suppose ω is an irrational angle. Then the rotation R_ω is minimal: all orbits of R_ω are dense in S^1 .

Proof: Take an arc $\gamma \subset S^1$. Then $R_\omega^n(\gamma)$, $n \geq 1$, is an arc of the same length as γ . Since S^1 has finite length, the arcs $\gamma, R_\omega(\gamma), R_\omega^2(\gamma), \dots$ cannot all be disjoint. Hence $R_\omega^n(\gamma) \cap R_\omega^m(\gamma) \neq \emptyset$ for some $0 \leq n < m$. But $R_\omega^n(\gamma) \cap R_\omega^m(\gamma) = R_\omega^n(\gamma \cap R_\omega^{m-n}(\gamma))$ so $\gamma \cap R_\omega^{m-n}(\gamma) \neq \emptyset$.

Thus for any $\varepsilon > 0$ there exists $k \geq 1$ such that $R_\omega^k = R_{k\omega}$ is the rotation by an angle ω' , $|\omega'| < \varepsilon$. Note that $\omega' \neq 0$ since ω is an irrational angle. Pick any $x \in S^1$. Let $n = \lceil 2\pi/|\omega'| \rceil$. Then points $x, R_{k\omega}(x) = R_\omega^k(x), R_{k\omega}^2(x) = R_\omega^{2k}(x), \dots, R_{k\omega}^n(x) = R_\omega^{nk}(x)$ divide S^1 into arcs of length $< \varepsilon$.

Uniform distribution

Let $T : S^1 \rightarrow S^1$ be a homeomorphism and $x \in S^1$. Consider the orbit $x, T(x), T^2(x), \dots, T^n(x), \dots$

Let $\gamma \subset S^1$ be an arc. By $N(x, \gamma; n)$ denote the number of integers $k \in \{0, 1, \dots, n-1\}$ such that $T^k(x) \in \gamma$. The orbit of x is **uniformly distributed** in S^1 if

$$\lim_{n \rightarrow \infty} \frac{N(x, \gamma_1; n)}{N(x, \gamma_2; n)} = 1$$

for any two arcs γ_1 and γ_2 of the same length.

An equivalent condition:

$$\lim_{n \rightarrow \infty} \frac{N(x, \gamma_1; n)}{N(x, \gamma_2; n)} = \frac{\text{length}(\gamma_1)}{\text{length}(\gamma_2)}$$

for any arcs γ_1 and γ_2 .

Another equivalent condition:

$$\lim_{n \rightarrow \infty} \frac{N(x, \gamma; n)}{n} = \frac{\text{length}(\gamma)}{2\pi}$$

for any arc γ .

Theorem (Kronecker-Weyl) Suppose ω is an irrational angle. Then all orbits of the rotation R_ω are uniformly distributed in S^1 .

Fractional linear transformations of S^1

A **fractional linear transformation** of the complex plane \mathbb{C} is given by

$$f(z) = \frac{az + b}{cz + d}, \quad a, b, c, d \in \mathbb{C}.$$

How can we tell if $f(S^1) = S^1$? This happens in the case

$$f(z) = e^{i\psi} \frac{z - z_0}{\bar{z}_0 z - 1},$$

where $|z_0| \neq 1$ and $\psi \in \mathbb{R}$. Indeed, if $z \in S^1$ then

$$z = e^{i\alpha}, \quad z_0 = re^{i\beta},$$

$$z - z_0 = e^{i\alpha} - re^{i\beta} = e^{i\alpha}(1 - re^{i\beta}e^{-i\alpha}),$$

$$\bar{z}_0 z - 1 = re^{-i\beta}e^{i\alpha} - 1 \quad \text{so that } f(z) \in S^1.$$

Fractional linear transformations of S^1

$$S^1 = \{z \in \mathbb{C} : |z| = 1\},$$
$$f : S^1 \rightarrow S^1,$$

$$f(z) = -e^{i\omega} \frac{z - z_0}{\bar{z}_0 z - 1},$$

where $z \in \mathbb{C}$, $|z_0| \neq 1$ and $\omega \in \mathbb{R}$.

Fractional linear transformations of S^1 form a **group**. Rotations of the circle form a **subgroup** ($z_0 = 0$).

f is orientation-preserving if $|z_0| < 1$ and orientation-reversing if $|z_0| > 1$.

$$f(z) = \frac{az + b}{cz + d}, \quad g(z) = \frac{a'z + b'}{c'z + d'},$$

$$f(g(z)) = \frac{a \frac{a'z + b'}{c'z + d'} + b}{c \frac{a'z + b'}{c'z + d'} + d} = \frac{(aa' + bc')z + ab' + bd'}{(ca' + dc')z + cb' + dd'},$$

$$\frac{az + b}{cz + d} \mapsto \begin{pmatrix} a & b \\ c & d \end{pmatrix}.$$

Composition of fractional linear transformations corresponds to matrix multiplication. Moreover, the action of f on the circle corresponds to the action of a linear transformation on lines going through the origin.

$$f(z) = -e^{i\omega} \frac{z - z_0}{\bar{z}_0 z - 1},$$
$$-e^{i\omega/2} \begin{pmatrix} e^{i\omega/2} & -z_0 e^{i\omega/2} \\ -\bar{z}_0 e^{-i\omega/2} & e^{-i\omega/2} \end{pmatrix}.$$

$$\det = 1 - |z_0|^2, \quad \text{Tr} = e^{i\omega/2} + e^{-i\omega/2} = 2 \cos(\omega/2).$$

Characteristic equation:

$$\lambda^2 - 2 \cos(\omega/2) \lambda + 1 - |z_0|^2 = 0.$$

Discriminant:

$$D = \cos^2(\omega/2) - 1 + |z_0|^2 = |z_0|^2 - \sin^2(\omega/2).$$

If $D < 0$ then f is **elliptic**.

If $D = 0$ then f is **parabolic**.

If $D > 0$ then f is **hyperbolic**.

- Theorem (i)** If f is elliptic then f has no fixed points and is topologically conjugate to a rotation.
- (ii)** If f is parabolic then f has a unique fixed point, which is neutral. Besides, the fixed point is weakly semi-attracting and semi-repelling.
- (iii)** If f is hyperbolic then f has two fixed points; one is attracting, the other is repelling.

Example. Given $\omega \in (0, \pi)$, the one-parameter family

$$f_r(z) = e^{i\omega} \frac{z - r}{1 - rz}, \quad 0 \leq r < 1$$

undergoes a saddle-node bifurcation at $r = r_0 = |\sin(\omega/2)|$.